

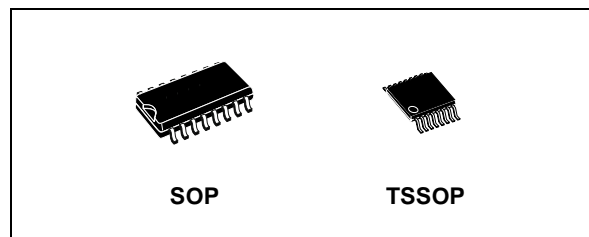
## SYNCHRONOUS PRESETTABLE 4-BIT COUNTER

- **HIGH SPEED:**  
 $f_{MAX} = 180 \text{ MHz (TYP.) at } V_{CC} = 3.3 \text{ V}$
- **COMPATIBLE WITH TTL OUTPUTS**
- **LOW POWER DISSIPATION:**  
 $I_{CC} = 4 \mu\text{A (MAX.) at } T_A = 25^\circ\text{C}$
- **LOW NOISE:**  
 $V_{OLP} = 0.3\text{V (TYP.) at } V_{CC} = 3.3\text{V}$
- **75Ω TRANSMISSION LINE DRIVING CAPABILITY**
- **SYMMETRICAL OUTPUT IMPEDANCE:**  
 $|I_{OH}| = I_{OL} = 12\text{mA (MIN) at } V_{CC} = 3.0 \text{ V}$
- **PCI BUS LEVELS GUARANTEED AT 24 mA**
- **BALANCED PROPAGATION DELAYS:**  
 $t_{PLH} \equiv t_{PHL}$
- **OPERATING VOLTAGE RANGE:**  
 $V_{CC(OPR)} = 2\text{V to } 3.6\text{V (1.2V Data Retention)}$
- **PIN AND FUNCTION COMPATIBLE WITH 74 SERIES 161**
- **IMPROVED LATCH-UP IMMUNITY**

### DESCRIPTION

The 74LVQ161 is a low voltage CMOS SYNCHRONOUS PRESETTABLE COUNTER fabricated with sub-micron silicon gate and double-layer metal wiring C<sup>2</sup>MOS technology. It is ideal for low power and low noise 3.3V applications. It is a 4 bit binary counter with Asynchronous Clear.

The circuit have four fundamental modes of operation, in order of preference: synchronous



**Table 1: Order Codes**

PACKAGE	T & R
SOP	74LVQ161MTR
TSSOP	74LVQ161TTR

reset, parallel load, count-up and hold. Four control inputs, Master Reset (CLEAR), Parallel Enable Input (PE) and Count Enable Carry Input (TE), determine the mode of operation as shown in the Truth Table. A LOW signal on CLEAR overrides counting and parallel loading and sets all outputs on LOW state. A LOW signal on LOAD overrides counting and allows information on Parallel Data Qn inputs to be loaded into the flip-flops on the next rising edge of CLOCK. With LOAD and CLEAR, PE and TE permit counting when both are high. Conversely, a LOW signal on either PE and TE inhibits counting. All inputs and outputs are equipped with protection circuits against static discharge, giving them 2KV ESD immunity and transient excess voltage.

**Figure 1: Pin Connection And IEC Logic Symbols**

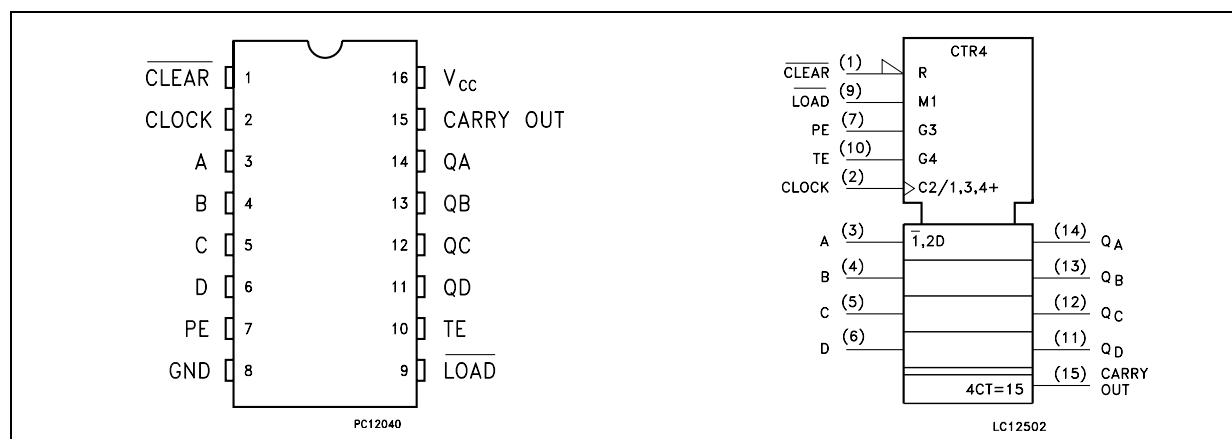


Figure 2: Input And Output Equivalent Circuit

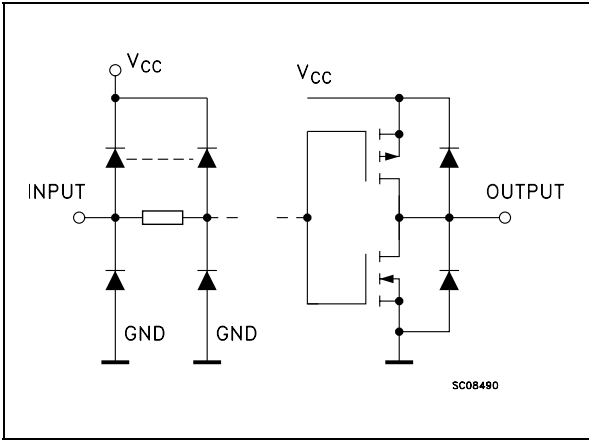


Table 2: Pin Description

PIN N°	SYMBOL	NAME AND FUNCTION
1	CLEAR	Asynchronous Master Reset
2	CLOCK	Clock Input (LOW to HIGH Edge Trigger)
3, 4, 5, 6	A, B, C, D	Data Inputs
7	PE	Count Enable Input
10	TE	Count Enable Carry Input
9	LOAD	Parallel Enable Input
14, 13, 12, 11	QA to QD	Flip-Flop Outputs
15	CARRY OUT	Terminal Count Output
8	GND	Ground (0V)
16	VCC	Positive Supply Voltage

Table 3: Truth Table

INPUTS					OUTPUTS				FUNCTION
CLEAR	LOAD	PE	TE	CK					
L	X	X	X	X	L	L	L	L	RESET TO "0"
H	L	X	X		A	B	C	D	PRESET DATA
H	H	X	L		NO CHANGE				NO COUNT
H	H	L	X		NO CHANGE				NO COUNT
H	H	H	H		COUNT UP				COUNT
H	X	X	X		NO CHANGE				NO COUNT

X : Don't Care; A, B, C, D; Logic level of data input; CARRY OUT: TE x QA x QB x QC x QD

Figure 3: Logic Diagram

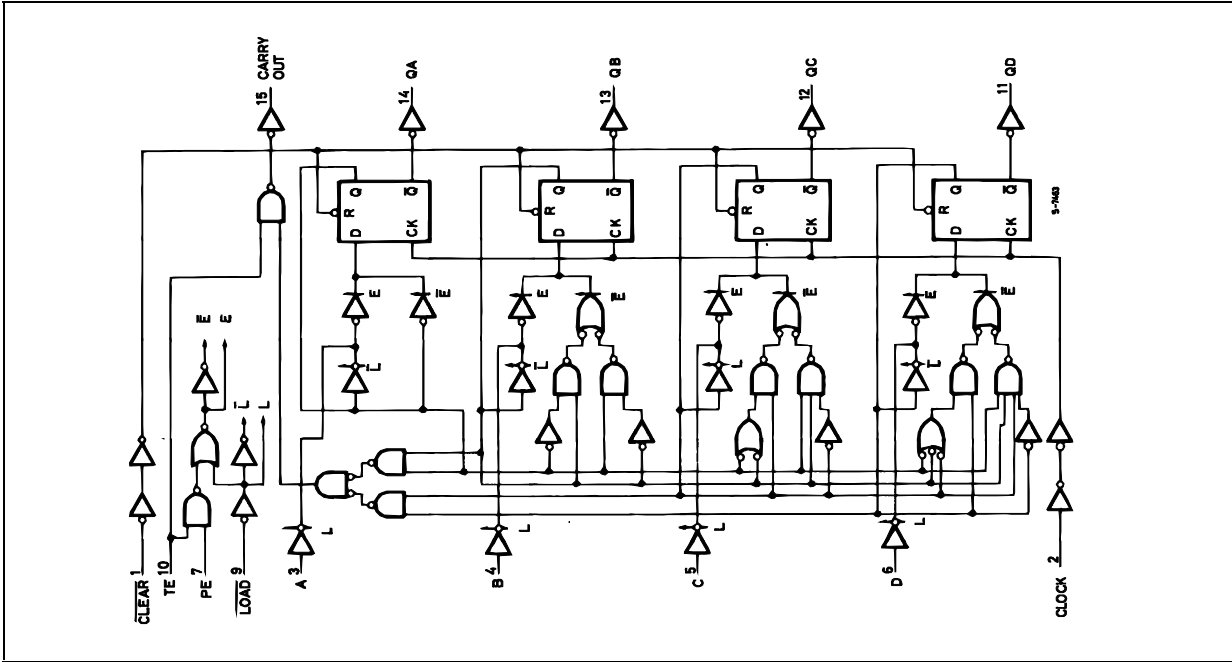


Figure 4: Timing Chart

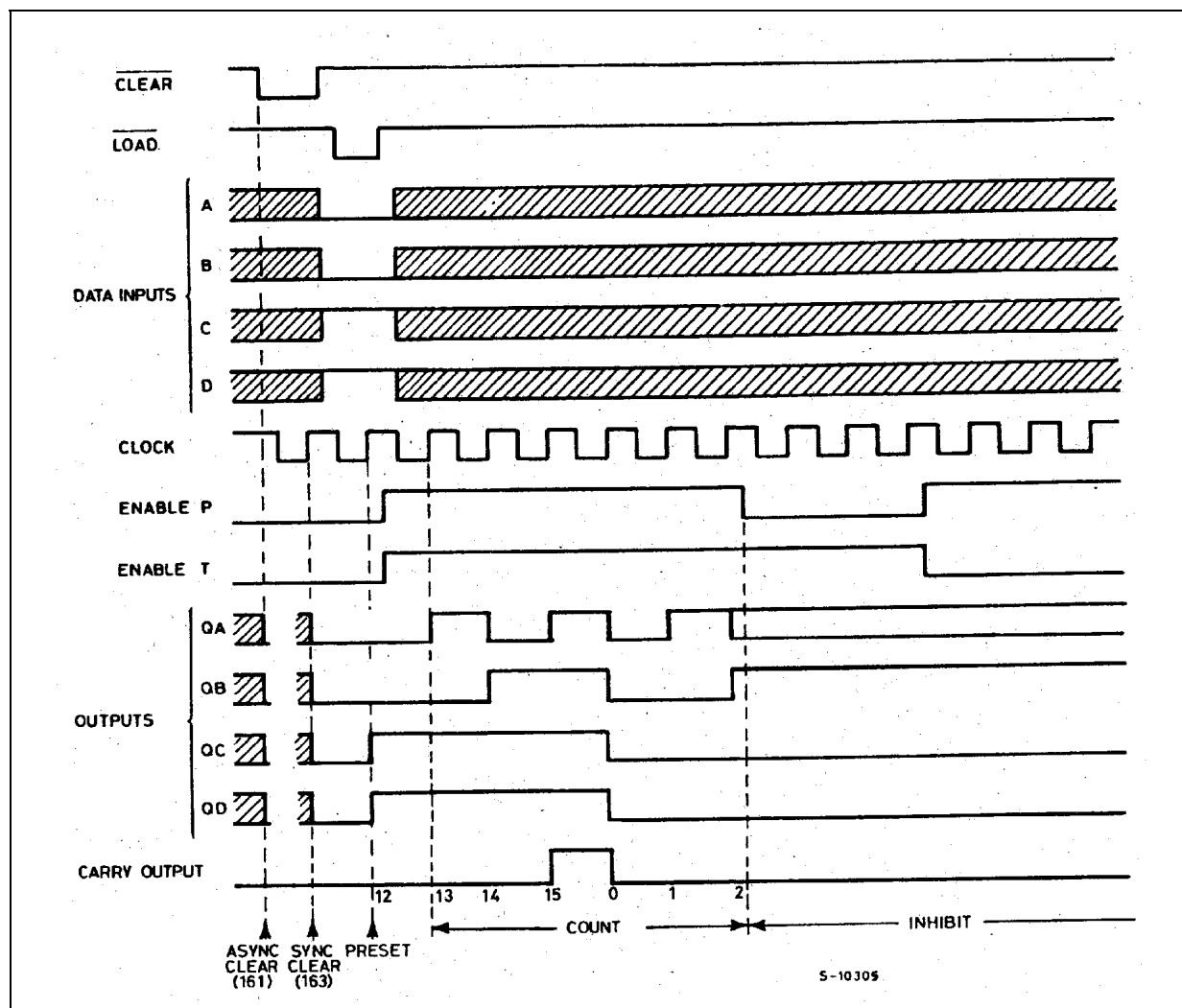


Table 4: Absolute Maximum Ratings

Symbol	Parameter	Value	Unit
$V_{CC}$	Supply Voltage	-0.5 to +7	V
$V_I$	DC Input Voltage	-0.5 to $V_{CC} + 0.5$	V
$V_O$	DC Output Voltage	-0.5 to $V_{CC} + 0.5$	V
$I_{IK}$	DC Input Diode Current	$\pm 20$	mA
$I_{OK}$	DC Output Diode Current	$\pm 20$	mA
$I_O$	DC Output Current	$\pm 50$	mA
$I_{CC}$ or $I_{GND}$	DC $V_{CC}$ or Ground Current	$\pm 300$	mA
$T_{stg}$	Storage Temperature	-65 to +150	°C
$T_L$	Lead Temperature (10 sec)	300	°C

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied.

Table 5: Recommended Operating Conditions

Symbol	Parameter	Value	Unit
$V_{CC}$	Supply Voltage (note 1)	2 to 3.6	V
$V_I$	Input Voltage	0 to $V_{CC}$	V
$V_O$	Output Voltage	0 to $V_{CC}$	V
$T_{op}$	Operating Temperature	-55 to 125	°C
dt/dv	Input Rise and Fall Time $V_{CC} = 3.0V$ (note 2)	0 to 10	ns/V

1) Truth Table guaranteed: 1.2V to 3.6V

2)  $V_{IN}$  from 0.8V to 2V

Table 6: DC Specifications

Symbol	Parameter	Test Condition		Value								Unit
		V <sub>CC</sub> (V)		T <sub>A</sub> = 25°C			-40 to 85°C		-55 to 125°C			
				Min.	Typ.	Max.	Min.	Max.	Min.	Max.		
V <sub>IH</sub>	High Level Input Volt.	3.0 to 3.6		2.0			2.0		2.0		V	
V <sub>IL</sub>	Low Level Input Volt.				0.8		0.8		0.8		V	
V <sub>OH</sub>	High Level Output Voltage	3.0	I <sub>O</sub> =-50 μA	2.9	2.99		2.9		2.9		V	
			I <sub>O</sub> =-12 mA	2.58			2.48		2.48			
			I <sub>O</sub> =-24 mA				2.2		2.2			
V <sub>OL</sub>	Low Level Output Voltage	3.0	I <sub>O</sub> =50 μA		0.002	0.1		0.1		0.1	V	
			I <sub>O</sub> =12 mA		0	0.36		0.44		0.44		
			I <sub>O</sub> =24 mA					0.55		0.55		
I <sub>I</sub>	Input Leakage Current	3.6	V <sub>I</sub> = V <sub>CC</sub> or GND			± 0.1		± 1		± 1	μA	
I <sub>CC</sub>	Quiescent Supply Current	3.6	V <sub>I</sub> = V <sub>CC</sub> or GND			4		40		40	μA	
I <sub>OLD</sub>	Dynamic Output Current (note 1, 2)	3.6	V <sub>OLD</sub> = 0.8 V max				36		25		mA	
I <sub>OHD</sub>			V <sub>OHD</sub> = 2 V min				-25		-25		mA	

1) Maximum test duration 2ms, one output loaded at time

2) Incident wave switching is guaranteed on transmission lines with impedances as low as 75Ω

Table 7: Dynamic Switching Characteristics

Symbol	Parameter	Test Condition		Value						Unit	
		V <sub>CC</sub> (V)		T <sub>A</sub> = 25°C			-40 to 85°C		-55 to 125°C		
				Min.	Typ.	Max.	Min.	Max.	Min.		Max.
V <sub>OLP</sub>	Dynamic Low Voltage Quiet Output (note 1, 2)	3.3	C <sub>L</sub> = 50 pF		0.3	0.8					V
V <sub>OLV</sub>				-0.8	-0.3						
V <sub>IHD</sub>	Dynamic High Voltage Input (note 1, 3)	3.3		2							V
V <sub>ILD</sub>	Dynamic Low Voltage Input (note 1, 3)	3.3					0.8				

1) Worst case package.

2) Max number of outputs defined as (n). Data inputs are driven 0V to 3.3V, (n-1) outputs switching and one output at GND.

3) Max number of data inputs (n) switching. (n-1) switching 0V to 3.3V. Inputs under test switching: 3.3V to threshold ( $V_{ILD}$ ), 0V to threshold ( $V_{IHD}$ ),  $f = 1\text{MHz}$ .

Table 8: AC Electrical Characteristics ( $C_L = 50 \text{ pF}$ ,  $R_L = 500 \Omega$ , Input  $t_r = t_f = 3 \text{ ns}$ )

Symbol	Parameter	Test Condition		Value						Unit	
		V <sub>CC</sub> (V)		T <sub>A</sub> = 25°C			-40 to 85°C		-55 to 125°C		
				Min.	Typ.	Max.	Min.	Max.	Min.		Max.
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay Time CK to Q	2.7			8.0	13.0		15.0		17.0	ns
		3.3(*)			6.8	9.5		11.0		12.5	
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay Time CK to CARRY OUT	2.7			9.1	14.0		16.0		18.5	ns
		3.3(*)			7.5	10.5		12.0		14.0	
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay Time TE to CARRY OUT	2.7			5.6	10.0		11.5		13.0	ns
		3.3(*)			4.7	8.0		9.5		10.5	
t <sub>PHL</sub>	Propagation Delay Time CLR to Q	2.7			8.0	12.0		15.0		17.0	ns
		3.3(*)			6.1	9.5		11.0		12.5	
t <sub>PHL</sub>	Propagation Delay Time CLR to CARRY OUT	2.7			8.0	14.0		16.0		18.5	ns
		3.3(*)			6.7	10.5		12.0		14.0	
t <sub>W(L)</sub>	CLR Pulse Width, LOW (LOAD)	2.7		4.0	1.9		4.0		4.0		ns
		3.3(*)		3.0	1.9		3.0		3.0		
t <sub>W</sub>	CLOCK Pulse Width, HIGH or LOW	2.7		4.0	1.9		4.0		4.0		ns
		3.3(*)		3.0	1.9		3.0		3.0		
t <sub>s</sub>	Setup Time HIGH or LOW (INPUT to CLOCK)	2.7		5.0	2.5		5.0		5.0		ns
		3.3(*)		4.0	2.1		4.0		4.0		
t <sub>h</sub>	Hold Time HIGH or LOW (INPUT to CLOCK)	2.7		1	-1.3		1		1		ns
		3.3(*)		0.5	-1.0		0.5		0.5		
t <sub>s</sub>	Setup Time HIGH or LOW (LOAD to CLOCK)	2.7		3.0	1.5		3.0		3.0		ns
		3.3(*)		2.5	1.2		2.5		2.5		
t <sub>h</sub>	Hold Time HIGH or LOW (LOAD to CLOCK)	2.7		1	-0.6		1		1		ns
		3.3(*)		0.5	-0.5		0.5		0.5		
t <sub>s</sub>	Setup Time HIGH or LOW (PE or TE to CLOCK)	2.7		7.0	3.4		7.0		7.0		ns
		3.3(*)		6.0	3.0		6.0		6.0		
t <sub>h</sub>	Hold Time HIGH or LOW (PE or TE to CLOCK)	2.7		0	-2.6		0		0		ns
		3.3(*)		0	-2.2		0		0		
t <sub>REM</sub>	Recovery Time CLR to CK	2.7		1	-0.8		1		1		ns
		3.3(*)		0.5	-0.6		0.5		0.5		
f <sub>MAX</sub>	Maximum Clock Frequency	2.7		100	150		80		60		MHz
		3.3(*)		120	180		100		80		
t <sub>OSLH</sub> t <sub>OSHL</sub>	Output To Output Skew Time (note1, 2)	2.7			0.5	1.0		1.0		1.0	ns
		3.3(*)			0.5	1.0		1.0		1.0	

1) Skew is defined as the absolute value of the difference between the actual propagation delay for any two outputs of the same device switching in the same direction, either HIGH or LOW ( $t_{OSLH} = |t_{PLHm} - t_{PLHn}|$ ,  $t_{OSHL} = |t_{PHLm} - t_{PHLn}|$ )

2) Parameter guaranteed by design

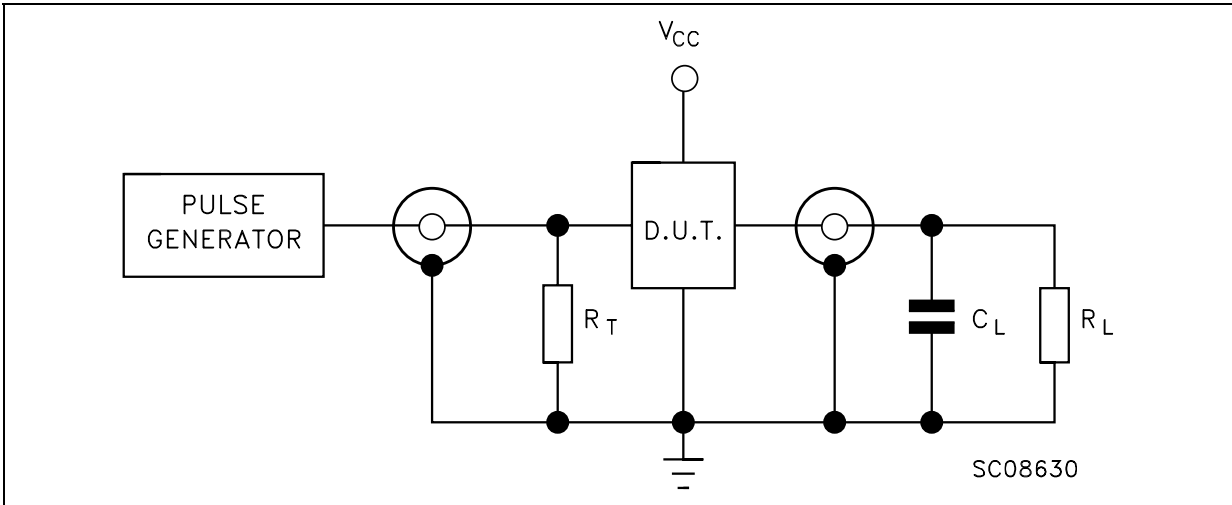
(\*) Voltage range is  $3.3\text{V} \pm 0.3\text{V}$

Table 9: Capacitive Characteristics

Symbol	Parameter	Test Condition		Value						Unit	
		V <sub>CC</sub> (V)		T <sub>A</sub> = 25°C			-40 to 85°C		-55 to 125°C		
				Min.	Typ.	Max.	Min.	Max.	Min.		Max.
C <sub>IN</sub>	Input Capacitance	3.3			4						pF
C <sub>PD</sub>	Power Dissipation Capacitance (note 1)	3.3	f <sub>IN</sub> = 10MHz		16						pF

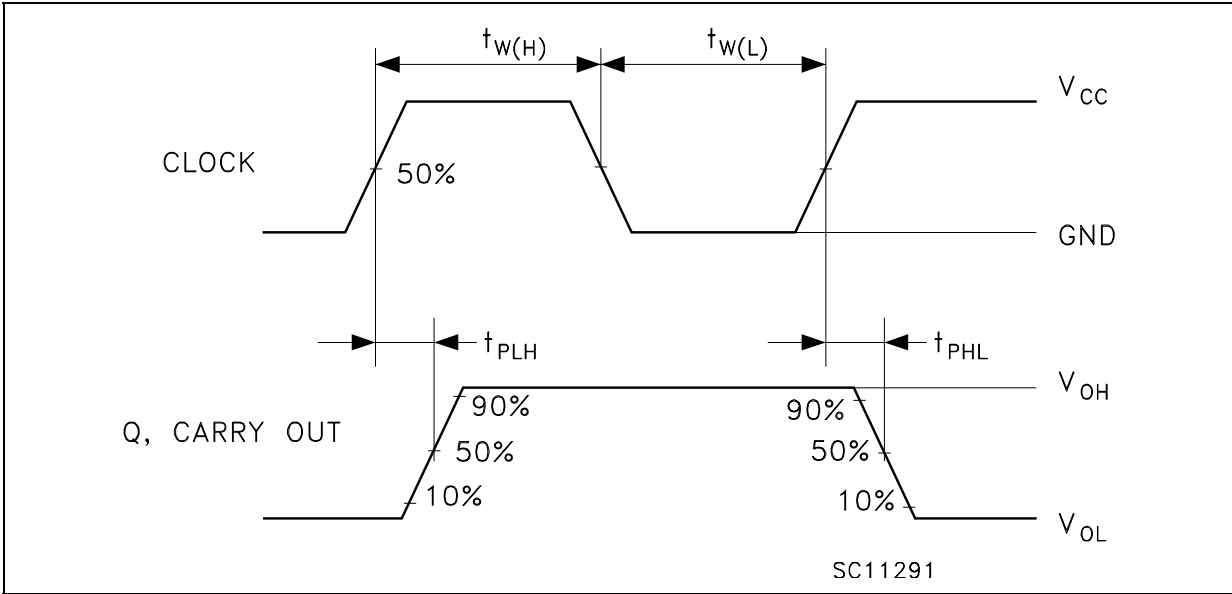
1) C<sub>PD</sub> is defined as the value of the IC's internal equivalent capacitance which is calculated from the operating current consumption without load. (Refer to Test Circuit). Average operating current can be obtained by the following equation. I<sub>CC(opr)</sub> = C<sub>PD</sub> × V<sub>CC</sub> × f<sub>IN</sub> + I<sub>CC</sub>/n (per circuit)

Figure 5: Test Circuit



C<sub>L</sub> = 50pF or equivalent (includes jig and probe capacitance)  
R<sub>L</sub> = 500Ω or equivalent  
R<sub>T</sub> = Z<sub>OUT</sub> of pulse generator (typically 50Ω)

Figure 6: Waveform - Propagation Delays, Count Mode (f=1MHz; 50% duty cycle)



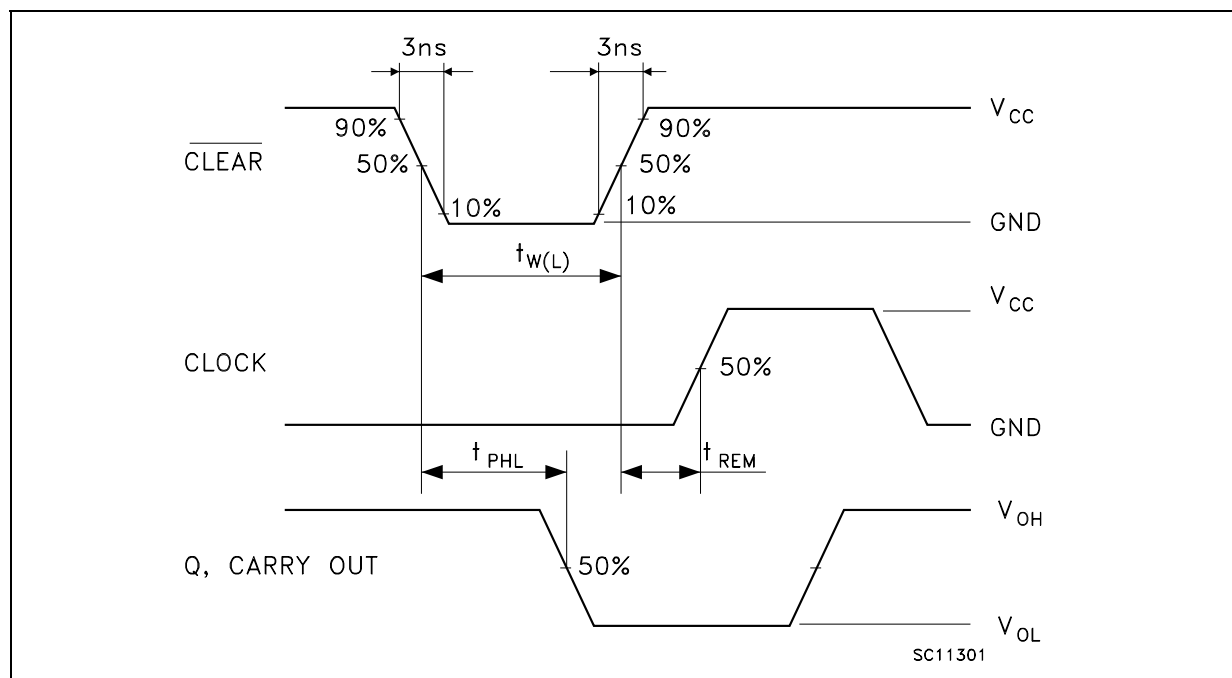
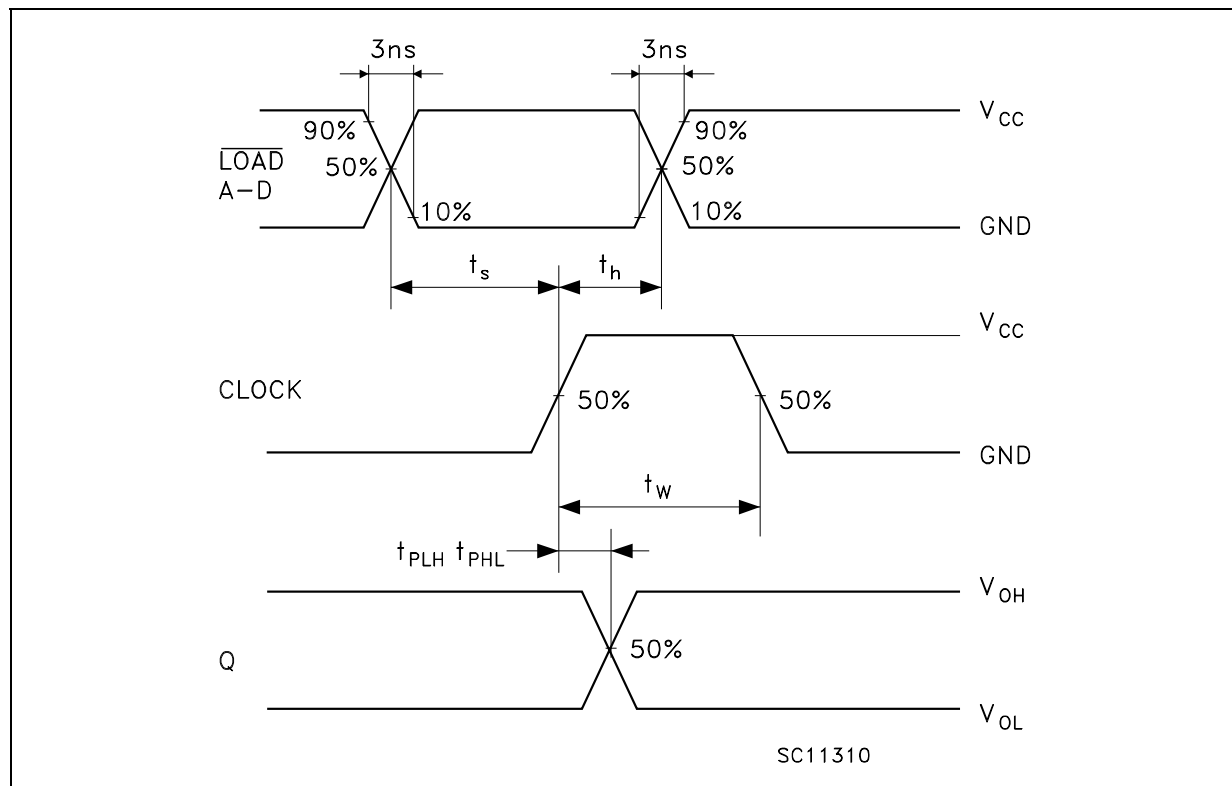
**Figure 7: Waveform - Propagation Delays Clear Mode ( $f=1\text{MHz}$ ; 50% duty cycle)****Figure 8: Waveform - Propagation Delays Preset Mode ( $f=1\text{MHz}$ ; 50% duty cycle)**

Figure 9: Waveform - Propagation Delays Countable Mode (f=1MHz; 50% duty cycle)

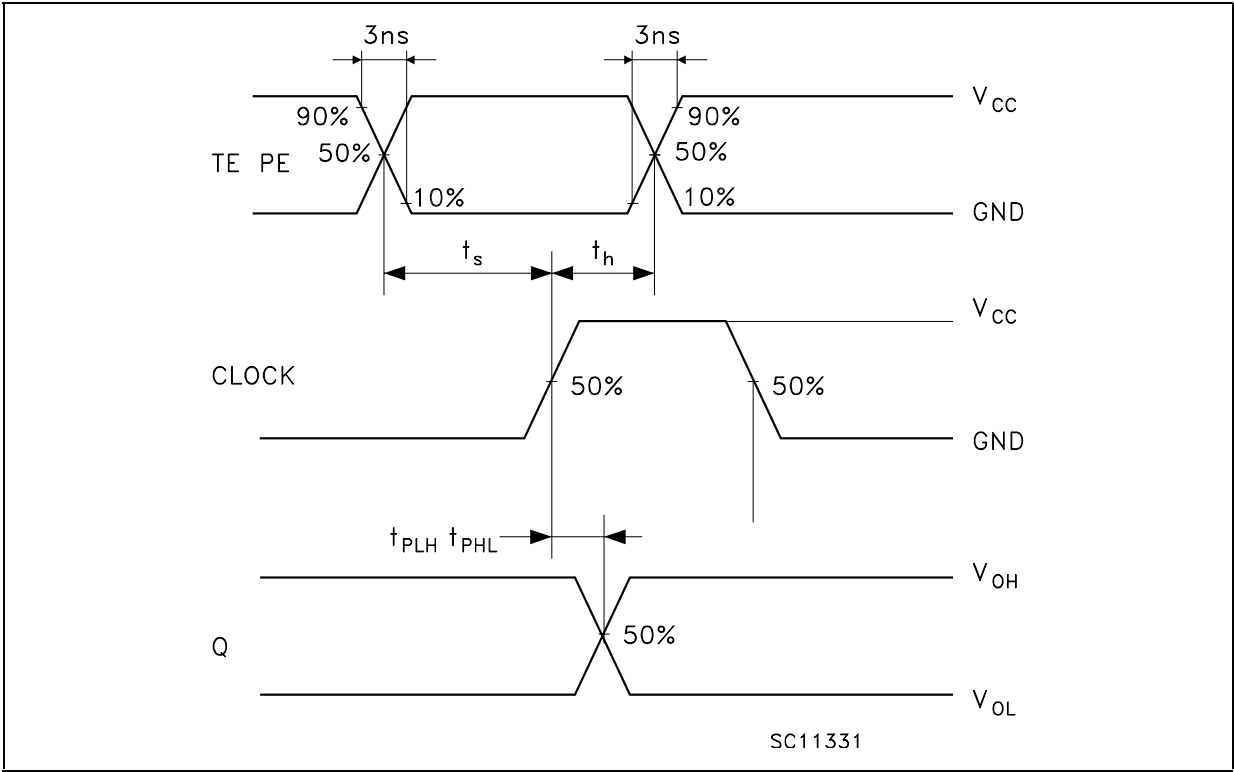
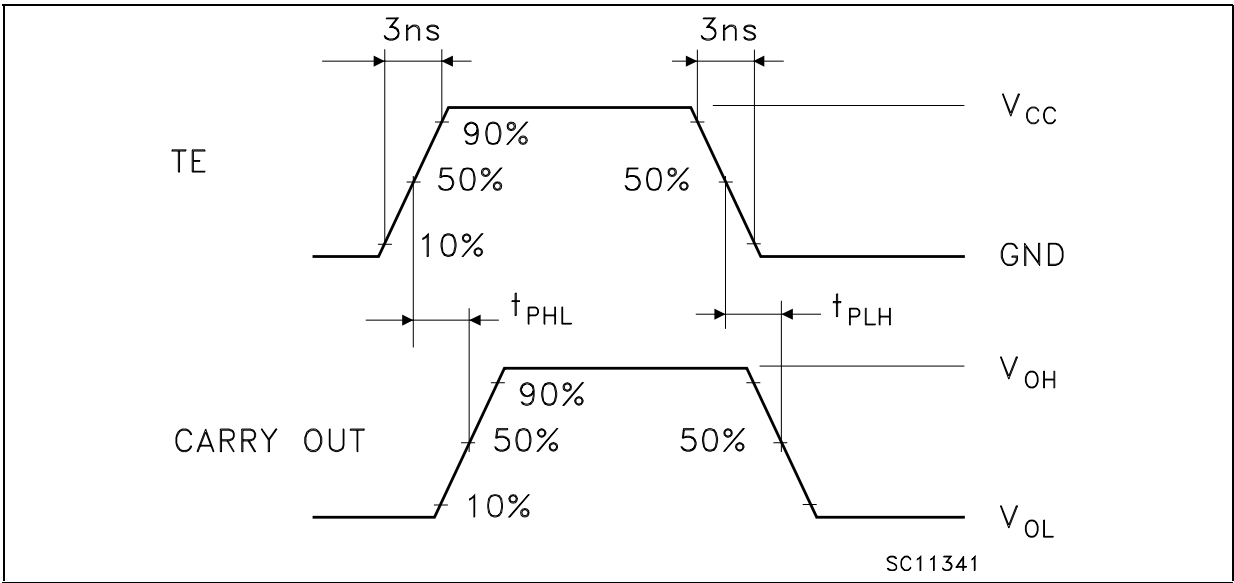


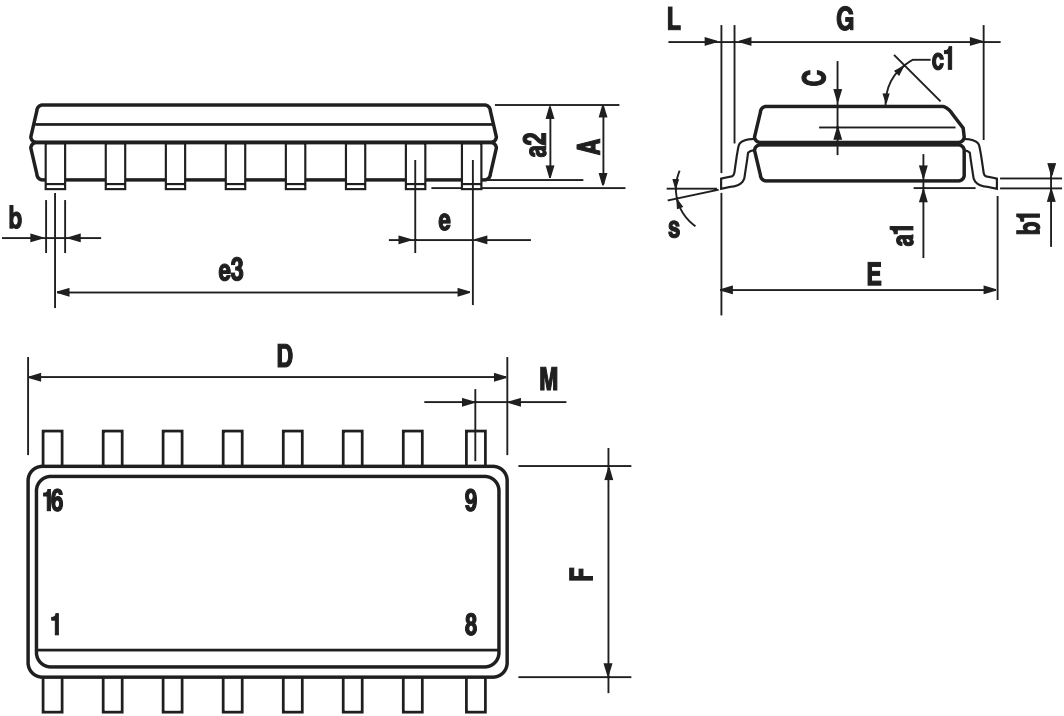
Figure 10: Waveform - Propagation Delays Cascade Mode (f=1MHz; 50% duty cycle)





SO-16 MECHANICAL DATA

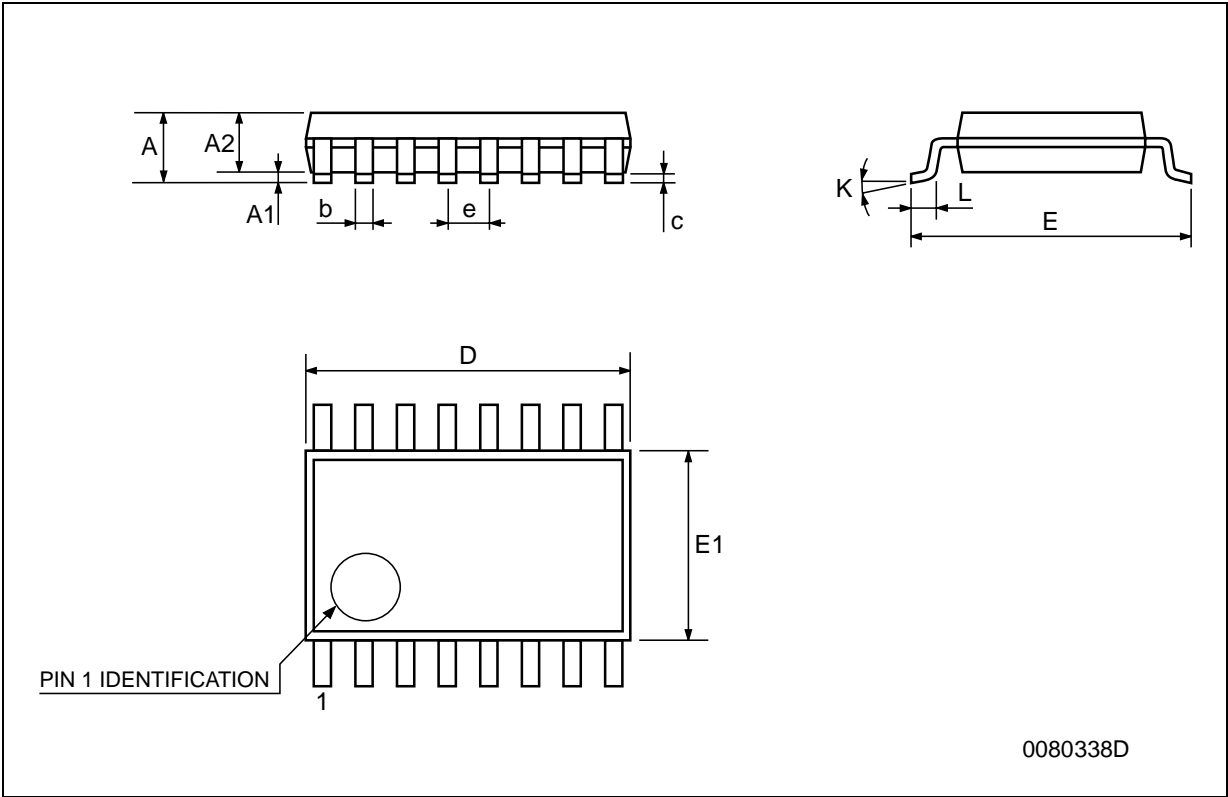
DIM.	mm.			inch		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
A			1.75			0.068
a1	0.1		0.25	0.004		0.010
a2			1.64			0.063
b	0.35		0.46	0.013		0.018
b1	0.19		0.25	0.007		0.010
C		0.5			0.019	
c1	45° (typ.)					
D	9.8		10	0.385		0.393
E	5.8		6.2	0.228		0.244
e		1.27			0.050	
e3		8.89			0.350	
F	3.8		4.0	0.149		0.157
G	4.6		5.3	0.181		0.208
L	0.5		1.27	0.019		0.050
M			0.62			0.024
S	8° (max.)					



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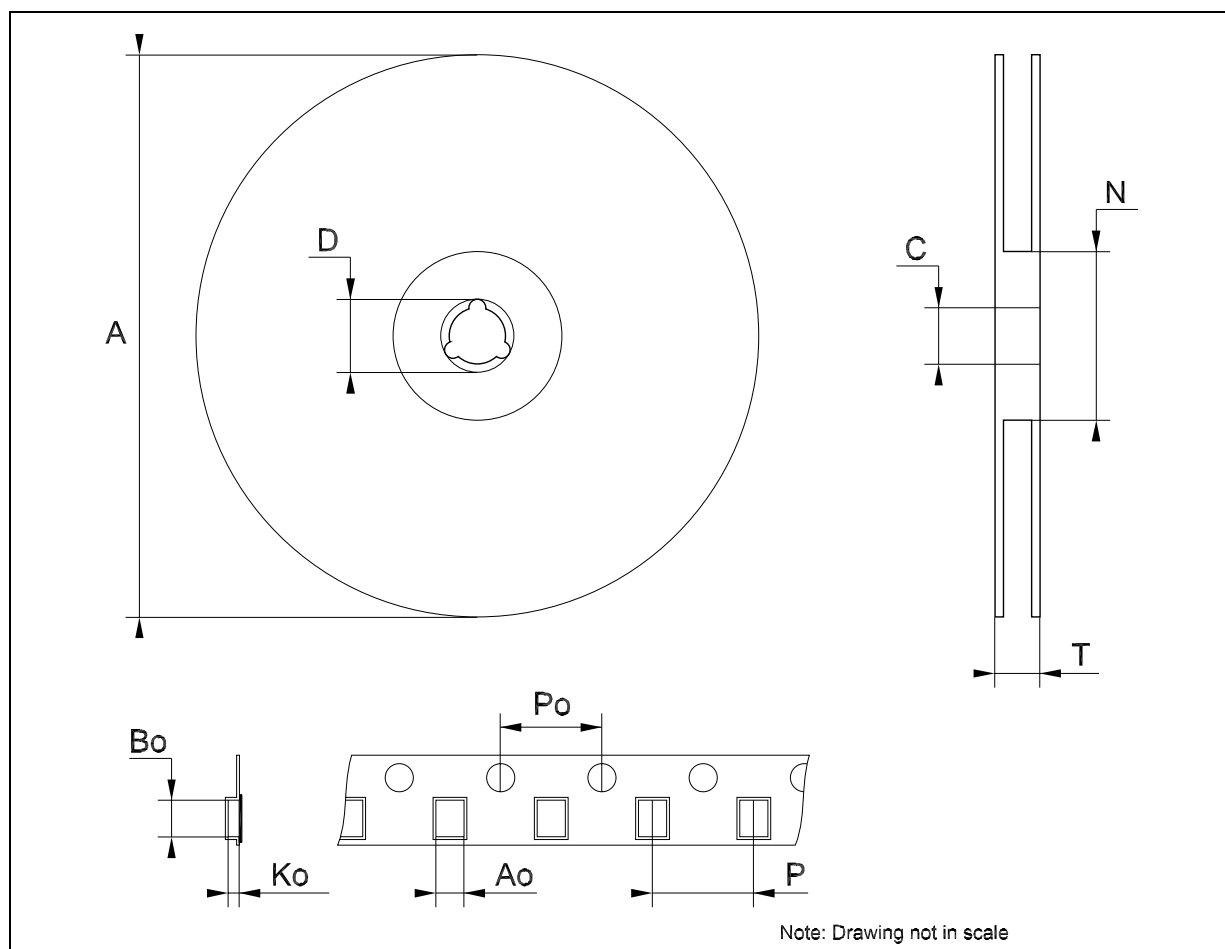
TSSOP16 MECHANICAL DATA

DIM.	mm.			inch		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
A			1.2			0.047
A1	0.05		0.15	0.002	0.004	0.006
A2	0.8	1	1.05	0.031	0.039	0.041
b	0.19		0.30	0.007		0.012
c	0.09		0.20	0.004		0.0079
D	4.9	5	5.1	0.193	0.197	0.201
E	6.2	6.4	6.6	0.244	0.252	0.260
E1	4.3	4.4	4.48	0.169	0.173	0.176
e		0.65 BSC			0.0256 BSC	
K	0°		8°	0°		8°
L	0.45	0.60	0.75	0.018	0.024	0.030



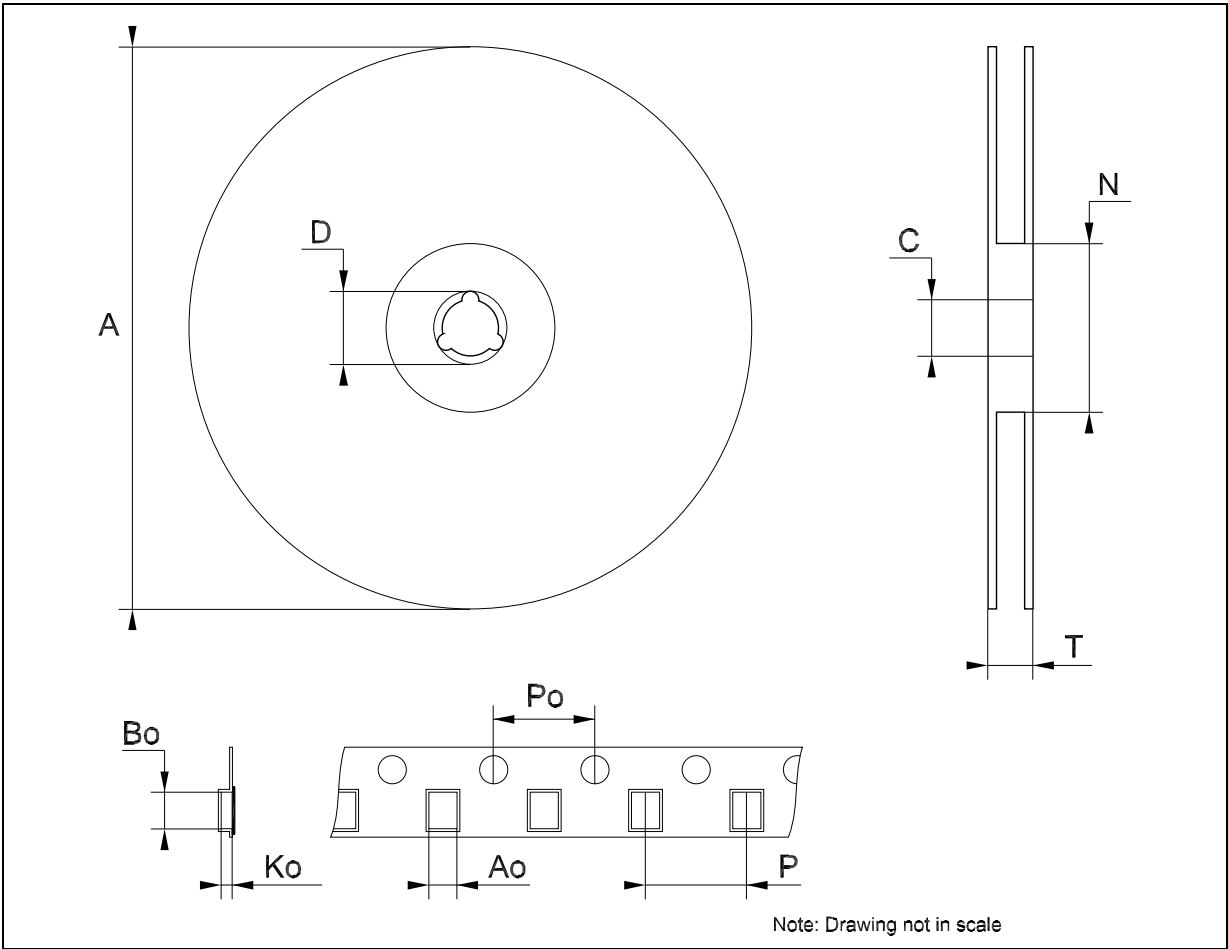
# Tape & Reel SO-16 MECHANICAL DATA

DIM.	mm.			inch		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
A			330			12.992
C	12.8		13.2	0.504		0.519
D	20.2			0.795		
N	60			2.362		
T			22.4			0.882
Ao	6.45		6.65	0.254		0.262
Bo	10.3		10.5	0.406		0.414
Ko	2.1		2.3	0.082		0.090
Po	3.9		4.1	0.153		0.161
P	7.9		8.1	0.311		0.319



Tape & Reel TSSOP16 MECHANICAL DATA

DIM.	mm.			inch		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
A			330			12.992
C	12.8		13.2	0.504		0.519
D	20.2			0.795		
N	60			2.362		
T			22.4			0.882
Ao	6.7		6.9	0.264		0.272
Bo	5.3		5.5	0.209		0.217
Ko	1.6		1.8	0.063		0.071
Po	3.9		4.1	0.153		0.161
P	7.9		8.1	0.311		0.319



**Table 10: Revision History**

Date	Revision	Description of Changes
29-Jul-2004	2	Ordering Codes Revision - pag. 1.

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