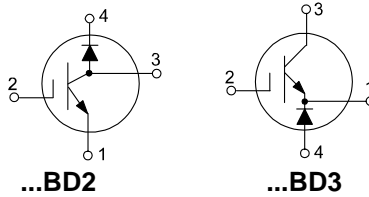


# HiPerFAST™ IGBT with HiPerFRED

**IXGN 50N60BD2**  
**IXGN 50N60BD3**

Buck & boost configurations

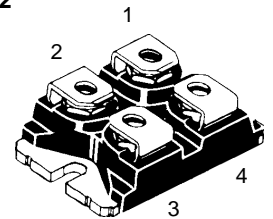


$V_{CES} = 600 \text{ V}$   
 $I_{C25} = 75 \text{ A}$   
 $V_{CE(sat)} = 2.5 \text{ V}$   
 $t_{fi} = 150 \text{ ns}$

	Symbol	Test Conditions	Maximum Ratings	
IGBT	$V_{CES}$	$T_J = 25^\circ\text{C to } 150^\circ\text{C}$	600	V
	$V_{CGR}$	$T_J = 25^\circ\text{C to } 150^\circ\text{C}; R_{GE} = 1 \text{ M}\Omega$	600	V
	$V_{GES}$	Continuous	$\pm 20$	V
	$V_{GEM}$	Transient	$\pm 30$	V
	$I_{C25}$	$T_C = 25^\circ\text{C}$	75	A
	$I_{C90}$	$T_C = 90^\circ\text{C}$	50	A
	$I_{CM}$	$T_C = 25^\circ\text{C}, 1 \text{ ms}$	200	A
	<b>SSOA (RBSOA)</b>	$V_{GE} = 15 \text{ V}, T_{VJ} = 125^\circ\text{C}, R_G = 10 \Omega$ Clamped inductive load, $L = 30 \mu\text{H}$	$I_{CM} = 100$ @ $0.8 V_{CES}$	A
Diode	$P_C$	$T_C = 25^\circ\text{C}$	250	W
	$V_{RRM}$		600	V
	$I_{FAVM}$	$T_C = 70^\circ\text{C}; \text{rectangular, } d = 50\%$	60	A
	$I_{FRM}$	$t_p < 10 \text{ ms}; \text{pulse width limited by } T_J$	600	A
	$P_D$	$T_C = 25^\circ\text{C}$	150	W
Case	$T_J$		-40 ... +150	$^\circ\text{C}$
	$T_{JM}$		150	$^\circ\text{C}$
	$T_{stg}$		-40 ... +150	$^\circ\text{C}$
	$M_d$	Mounting torque	1.5/13	Nm/lb.in.
		Terminal connection torque (M4)	1.5/13	Nm/lb.in.
	<b>Weight</b>		30	g
		Maximum lead temperature for soldering 1.6 mm (0.062 in.) from case for 10 s	300	$^\circ\text{C}$

SOT-227B, miniBLOC

E 153432



**IXGN50N60BD2**

1 = Emitter; 2 = Gate  
3 = Collector; 4 = Diode cathode

**IXGN50N60BD3**

1 = Emitter/Diode Cathode; 2 = Gate  
3 = Collector; 4 = Diode anode

## Features

- International standard package miniBLOC
- Aluminium nitride isolation
  - high power dissipation
- Isolation voltage 3000 V~
- Very high current, fast switching IGBT & FRED diode
- MOS Gate turn-on
  - drive simplicity
- Low collector-to-case capacitance
- Low package inductance (< 10 nH)
  - easy to drive and to protect
- Molding epoxies meet UL94 V-0 flammability classification

## Applications

- AC motor speed control
- DC servo and robot drives
- DC choppers
- Buck converters

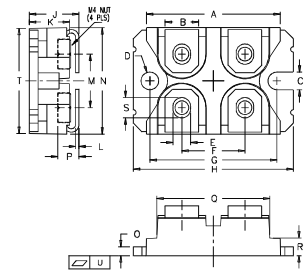
## Advantages

- Easy to mount with 2 screws
- Space savings
- High power density

Symbol	Test Conditions	Characteristic Values ( $T_J = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$BV_{CES}$	$I_C = 250 \mu\text{A}, V_{GE} = 0 \text{ V}$	600		V
$V_{GE(th)}$	$I_C = 250 \mu\text{A}, V_{CE} = V_{GE}$	2.5		5 V
$I_{CES}$	$V_{CE} = 0.8 \cdot V_{CES}$ $V_{GE} = 0 \text{ V}$			$T_J = 25^\circ\text{C}$ 200 $\mu\text{A}$ $T_J = 125^\circ\text{C}$ 1 mA
$I_{GES}$	$V_{CE} = 0 \text{ V}, V_{GE} = \pm 20 \text{ V}$			$\pm 100 \text{ nA}$
$V_{CE(sat)}$	$I_C = I_{C90}, V_{GE} = 15 \text{ V}$			2.5 V

Symbol	Test Conditions	Characteristic Values ( $T_J = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$g_{fs}$	$I_C = I_{C90}, V_{CE} = 10\text{ V}$ , Pulse test, $t \leq 300\text{ }\mu\text{s}$ , duty cycle $\leq 2\%$	35	50	S
$C_{ies}$	$V_{CE} = 25\text{ V}$ , $V_{GE} = 0\text{ V}$ , $f = 1\text{ MHz}$		4100	pF
$C_{oes}$			290	pF
$C_{res}$			50	pF
$Q_g$	$I_C = I_{C90}, V_{GE} = 15\text{ V}$ , $V_{CE} = 0.5 V_{CES}$		110	nC
$Q_{ge}$			30	nC
$Q_{gc}$			35	nC
$t_{d(on)}$	<b>Inductive load, <math>T_J = 25^\circ\text{C}</math></b> $I_C = I_{C90}, V_{GE} = 15\text{ V}$ , $L = 100\text{ }\mu\text{H}$ , $V_{CE} = 0.8 V_{CES}$ , $R_G = R_{off} = 2.7\text{ }\Omega$ Remarks: Switching times may increase for $V_{CE}(\text{Clamp}) > 0.8 \cdot V_{CES}$ , higher $T_J$ or increased $R_G$		50	ns
$t_{ri}$			50	ns
$t_{d(off)}$			110	250 ns
$t_{fi}$			150	220 ns
$E_{off}$			3.0	4.0 mJ
$t_{d(on)}$			50	ns
$t_{ri}$	<b>Inductive load, <math>T_J = 125^\circ\text{C}</math></b> $I_C = I_{C90}, V_{GE} = 15\text{ V}$ , $L = 100\text{ }\mu\text{H}$ $V_{CE} = 0.8 V_{CES}$ , $R_G = R_{off} = 2.7\text{ }\Omega$ Remarks: Switching times may increase for $V_{CE}(\text{Clamp}) > 0.8 \cdot V_{CES}$ , higher $T_J$ or increased $R_G$		60	ns
$E_{on}$			3.0	mJ
$t_{d(off)}$			200	ns
$t_{fi}$			250	ns
$E_{off}$			4.2	mJ
$R_{thJC}$				0.50 K/W
$R_{thCK}$		0.05		K/W

### miniBLOC, SOT-227 B



M4 screws (4x) supplied

Dim.	Millimeter		Inches	
	Min.	Max.	Min.	Max.
A	31.50	31.88	1.240	1.255
B	7.80	8.20	0.307	0.323
C	4.09	4.29	0.161	0.169
D	4.09	4.29	0.161	0.169
E	4.09	4.29	0.161	0.169
F	14.91	15.11	0.587	0.595
G	30.12	30.30	1.186	1.193
H	38.00	38.23	1.496	1.505
J	11.68	12.22	0.460	0.481
K	8.92	9.60	0.351	0.378
L	0.76	0.84	0.030	0.033
M	12.60	12.85	0.496	0.506
N	25.15	25.42	0.990	1.001
O	1.98	2.13	0.078	0.084
P	4.95	5.97	0.195	0.235
Q	26.54	26.90	1.045	1.059
R	3.94	4.42	0.155	0.174
S	4.72	4.85	0.186	0.191
T	24.59	25.07	0.968	0.987
U	-0.05	0.1	-0.002	0.004

### Reverse Diode (FRED) Characteristic Values

( $T_J = 25^\circ\text{C}$ , unless otherwise specified)

Symbol	Test Conditions	typ.	max.
$I_R$	$T_{VJ} = 25^\circ\text{C}$ $V_R = V_{RRM}$		650 $\mu\text{A}$
	$T_{VJ} = 150^\circ\text{C}$		2.5 mA
$V_F$	$I_F = 60\text{ A}$ , $T_{VJ} = 150^\circ\text{C}$		1.75 V
	Pulse test, $t \leq 300\text{ }\mu\text{s}$ , duty cycle $d \leq 2\%$ $T_{VJ} = 25^\circ\text{C}$		2.40 V
$I_{RM}$	$I_F = I_{C90}, V_{GE} = 0\text{ V}$ , $-di_F/dt = 100\text{ A}/\mu\text{s}$ $V_R = 540\text{ V}$		8.0 A
$t_{rr}$	$I_F = 1\text{ A}$ , $-di_F/dt = 50\text{ A}/\mu\text{s}$ , $V_R = 30\text{ V}$ $T_J = 25^\circ\text{C}$	35	ns
$R_{thJC}$			0.85 K/W

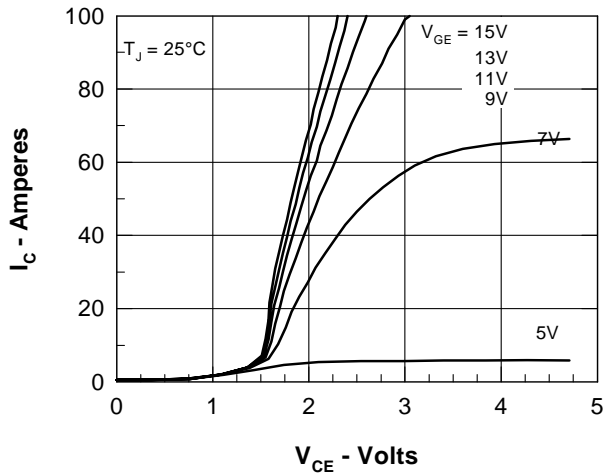


Fig. 1. Saturation Voltage Characteristics

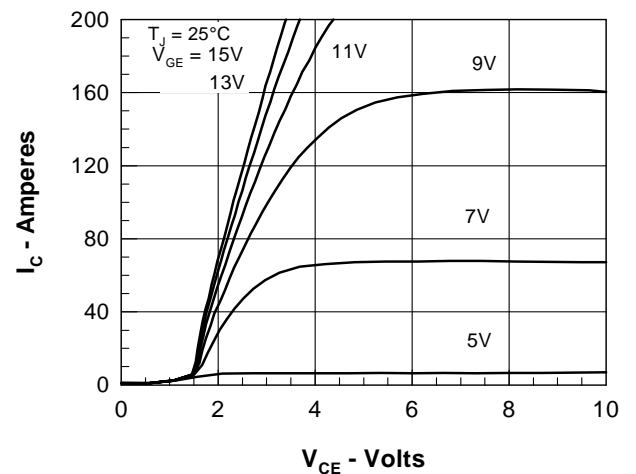


Fig. 2. Extended Output Characteristics

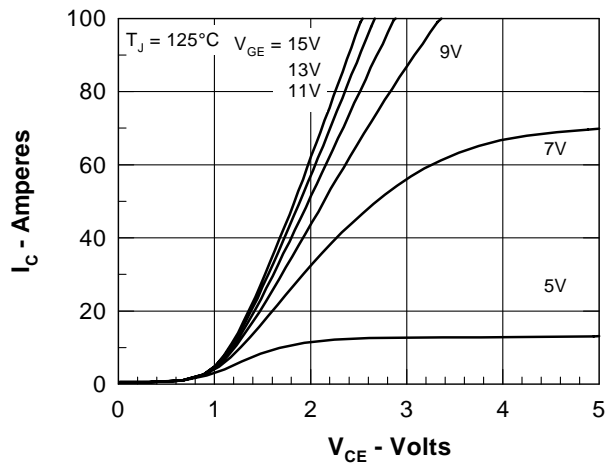


Fig. 3. Saturation Voltage Characteristics

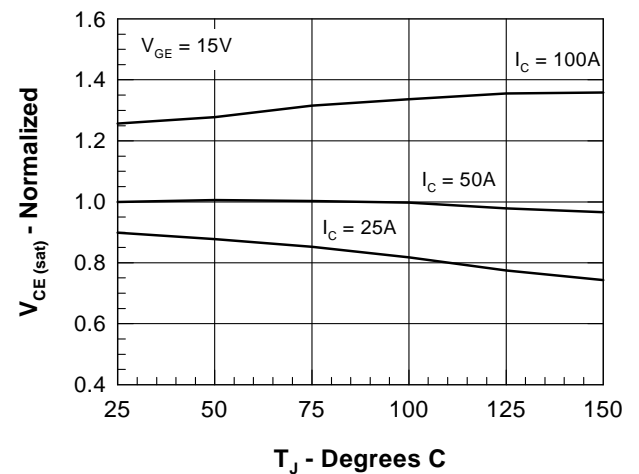


Fig. 4. Temperature Dependence of  $V_{CE(sat)}$

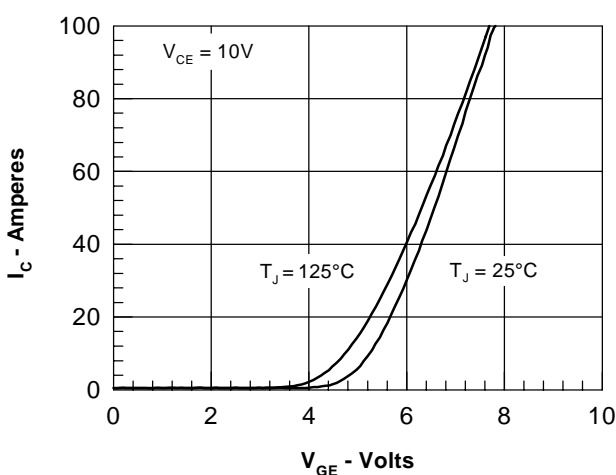


Fig. 5. Saturation Voltage Characteristics

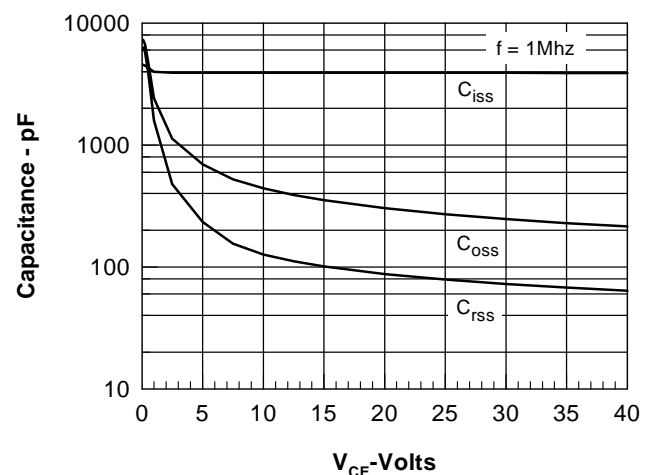


Fig. 6. Junction Capacitance Curves

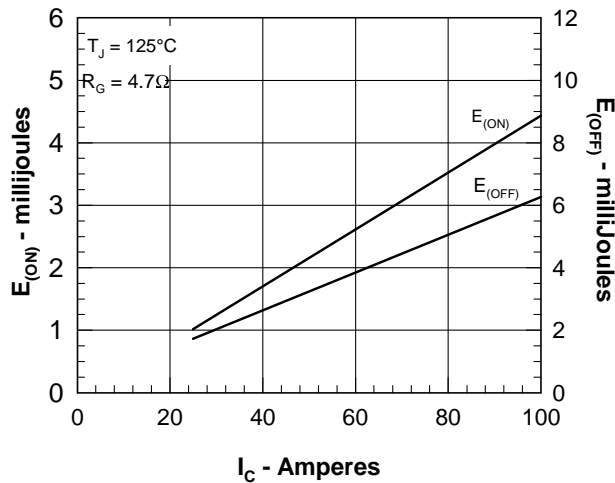


Fig. 7. Dependence of  $E_{ON}$  and  $E_{OFF}$  on  $I_C$ .

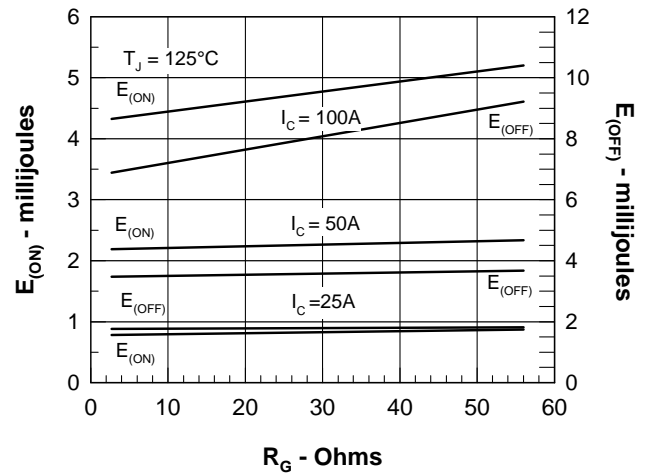


Fig. 8. Dependence of  $t_{fi}$  and  $E_{OFF}$  on  $R_G$ .

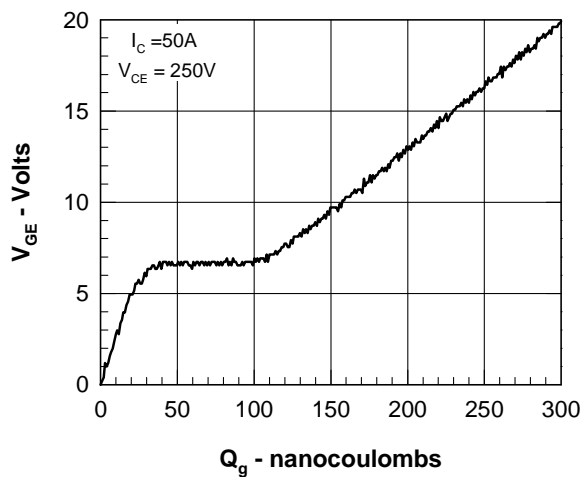


Fig. 9. Gate Charge

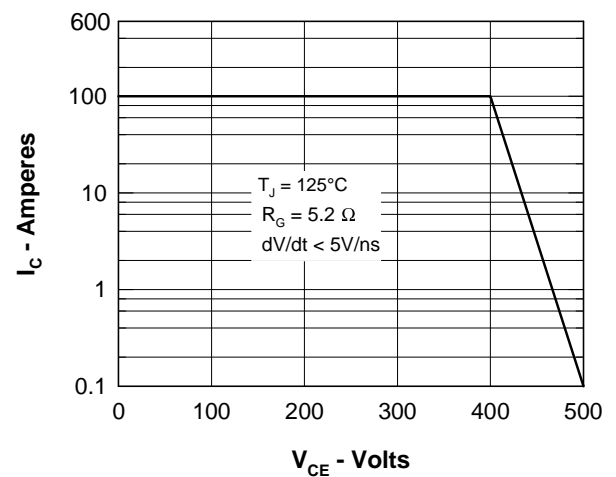


Fig. 10. Turn-off Safe Operating Area

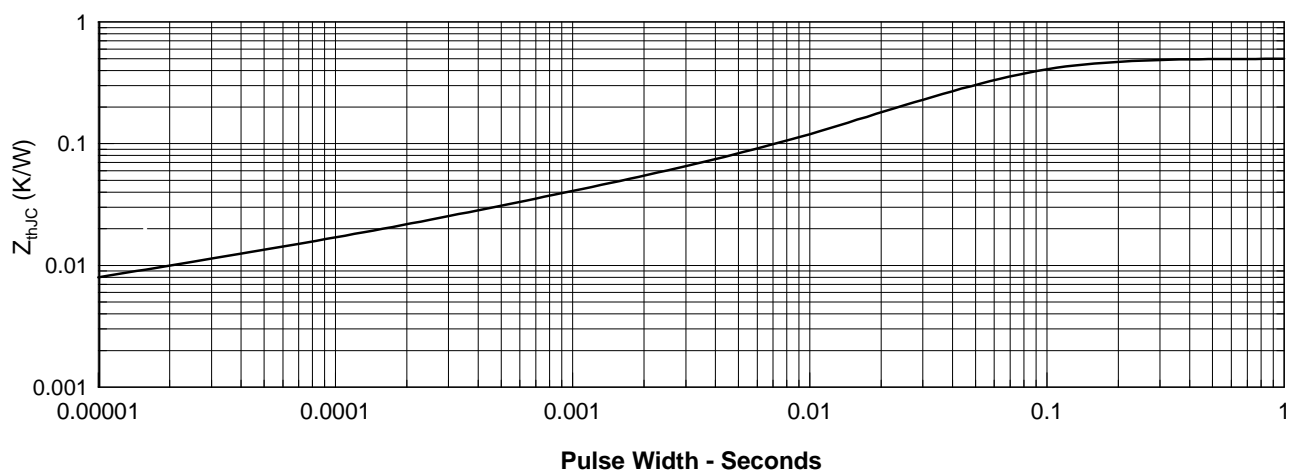


Fig. 11. Transient Thermal Resistance

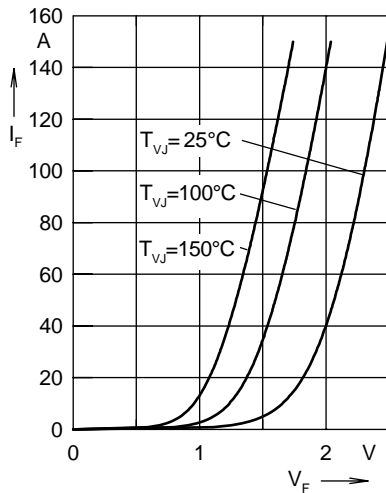


Fig. 12 Forward current  $I_F$  versus  $V_F$

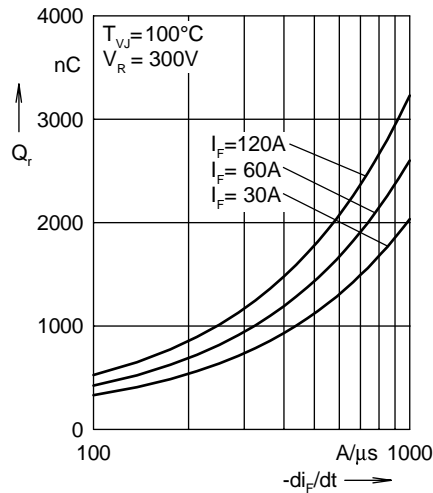


Fig. 13 Reverse recovery charge  $Q_r$  versus  $-di_F/dt$

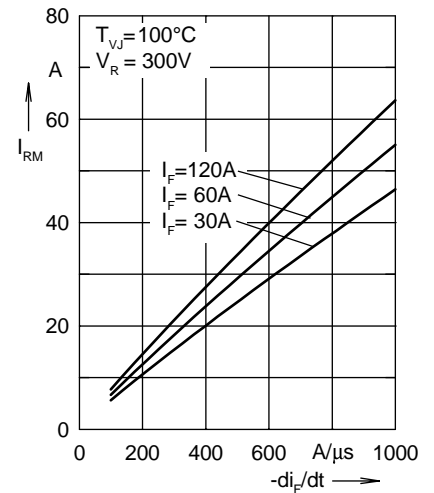


Fig. 14 Peak reverse current  $I_{RM}$  versus  $-di_F/dt$

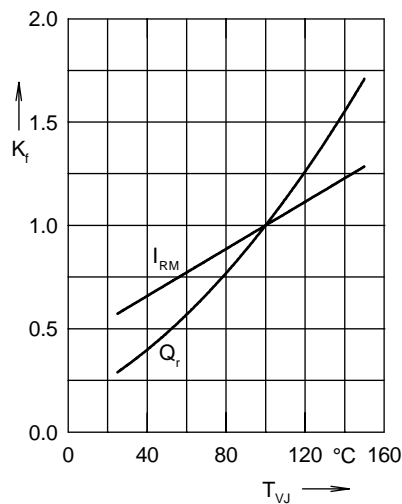


Fig. 15 Dynamic parameters  $Q_r$ ,  $I_{RM}$  versus  $T_{VJ}$

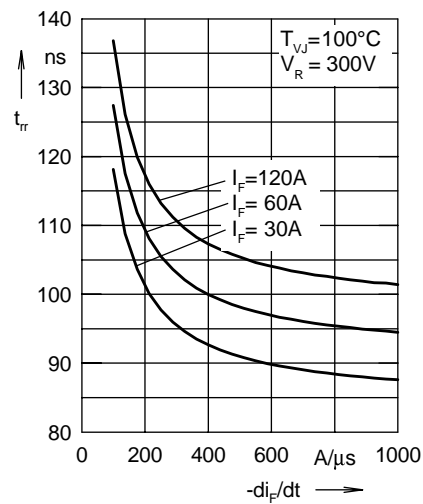


Fig. 16 Recovery time  $t_{rr}$  versus  $-di_F/dt$

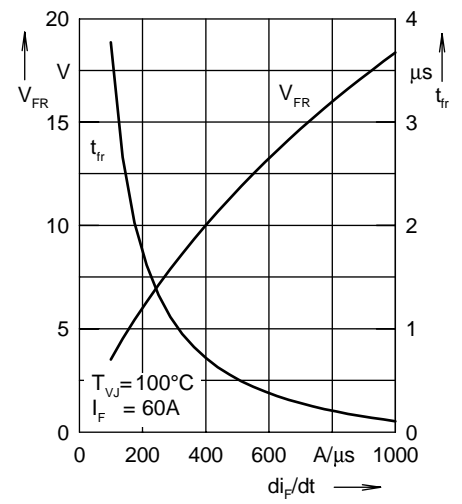


Fig. 17 Peak forward voltage  $V_{FR}$  and  $t_{fr}$  versus  $di_F/dt$

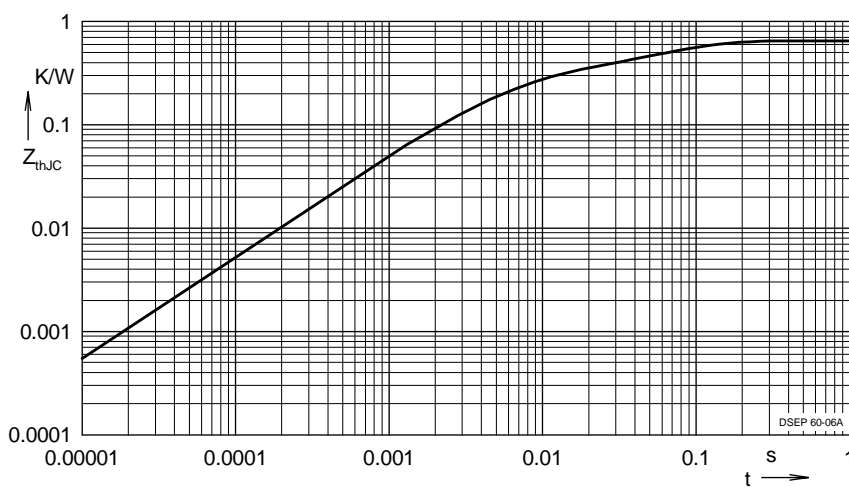


Fig. 18 Transient thermal resistance junction to case

Constants for  $Z_{thJC}$  calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.324	0.0052
2	0.125	0.0003
3	0.201	0.0385