

100351

Low Power Hex D-Type Flip-Flop

General Description

The 100351 contains six D-type edge-triggered, master/slave flip-flops with true and complement outputs, a pair of common Clock inputs (CP_a and CP_b) and common Master Reset (MR) input. Data enters a master when both CP_a and CP_b are LOW and transfers to the slave when CP_a and CP_b (or both) go HIGH. The MR input overrides all other inputs and makes the Q outputs LOW. All inputs have 50 k Ω pull-down resistors.

Features

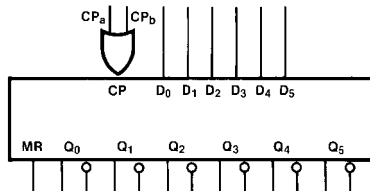
- 40% power reduction of the 100151
- 2000V ESD protection
- Pin/function compatible with 100151
- Voltage compensated operating range:
–4.2V to –5.7V
- Available to industrial grade temperature range

Ordering Code:

| Order Number | Package Number | Package Description |
|--------------|----------------|--|
| 100351SC | M24B | 24-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-013, 0.300 Wide |
| 100351PC | N24E | 24-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-010, 0.400 Wide |
| 100351QC | V28A | 28-Lead Plastic Lead Chip Carrier (PLCC), JEDEC MO-047, 0.450 Square |
| 100351QI | V28A | 28-Lead Plastic Lead Chip Carrier (PLCC), JEDEC MO-047, 0.450 Square Industrial Temperature Range (–40°C to +85°C) |

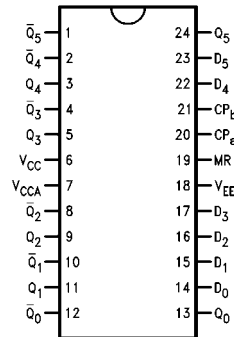
Devices also available in Tape and Reel. Specify by appending the suffix letter "X" to the ordering code.

Logic Symbol

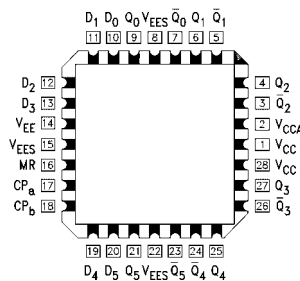


Connection Diagrams

24-Pin DIP/SOIC



28-Pin PLCC



Pin Descriptions

| Pin Names | Description |
|---------------------------|---------------------------------|
| D_0 – D_5 | Data Inputs |
| CP_a , CP_b | Common Clock Inputs |
| MR | Asynchronous Master Reset Input |
| Q_0 – Q_5 | Data Outputs |
| \bar{Q}_0 – \bar{Q}_5 | Complementary Data Outputs |

Truth Tables

(Each Flip-flop)

Synchronous Operation

| Inputs | | | | Outputs |
|--------|--------|--------|----|------------|
| D_n | CP_a | CP_b | MR | $Q_n(t+1)$ |
| L | ↗ | L | L | L |
| H | ↗ | L | L | H |
| L | L | ↗ | L | L |
| H | L | ↗ | L | H |
| X | H | ↗ | L | $Q_n(t)$ |
| X | ↗ | H | L | $Q_n(t)$ |
| X | L | L | L | $Q_n(t)$ |

Asynchronous Operation

| Inputs | | | | Outputs |
|--------|--------|--------|----|------------|
| D_n | CP_a | CP_b | MR | $Q_n(t+1)$ |
| X | X | X | H | L |

H = HIGH Voltage Level

L = LOW Voltage Level

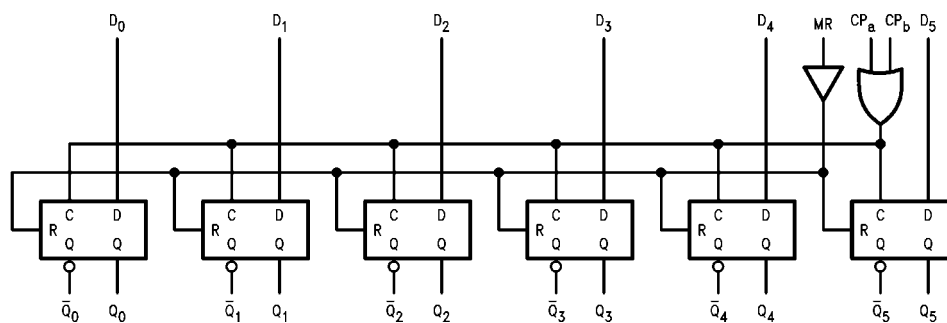
X = Don't Care

t = Time before CP positive transition

t+1 = Time after CP positive transition

↗ = LOW-to-HIGH transition

Logic Diagram



Absolute Maximum Ratings(Note 1)

| | |
|--|-------------------|
| Storage Temperature (T_{STG}) | -65°C to +150°C |
| Maximum Junction Temperature (T_J) | +150°C |
| V_{EE} Pin Potential to Ground Pin | -7.0V to +0.5V |
| Input Voltage (DC) | V_{EE} to +0.5V |
| Output Current (DC Output HIGH) | -50 mA |
| ESD (Note 2) | ≥2000V |

Recommended Operating Conditions

| | |
|-----------------------------|----------------|
| Case Temperature (T_C) | |
| Commercial | 0°C to +85°C |
| Industrial | -40°C to +85°C |
| Supply Voltage (V_{EE}) | -5.7V to -4.2V |

Note 1: The "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the Electrical Characteristics tables are not guaranteed at the absolute maximum rating. The "Recommended Operating Conditions" table will define the conditions for actual device operation.

Note 2: ESD testing conforms to MIL-STD-883, Method 3015.

Commercial Version**DC Electrical Characteristics** (Note 3)

$V_{EE} = -4.2V$ to $-5.7V$, $V_{CC} = V_{CCA} = GND$, $T_C = 0^\circ C$ to $+85^\circ C$

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|-----------|----------------------|-------|-------|-------|-------|--|
| V_{OH} | Output HIGH Voltage | -1025 | -955 | -870 | mV | $V_{IN} = V_{IH}$ (Max) Loading with or V_{IL} (Min) 50Ω to -2.0V |
| V_{OL} | Output LOW Voltage | -1830 | -1705 | -1620 | | |
| V_{OHC} | Output HIGH Voltage | -1035 | | | mV | $V_{IN} = V_{IH}$ (Min) Loading with or V_{IL} (Max) 50Ω to -2.0V |
| V_{OLC} | Output LOW Voltage | | | -1610 | | |
| V_{IH} | Input HIGH Voltage | -1165 | | -870 | mV | Guaranteed HIGH Signal for All Inputs |
| V_{IL} | Input LOW Voltage | -1830 | | -1475 | mV | Guaranteed LOW Signal for All Inputs |
| I_{IL} | Input LOW Current | 0.50 | | | μA | $V_{IN} = V_{IL}$ (Min) |
| I_{IH} | Input HIGH Current | | | | | |
| | MR | | | 350 | μA | $V_{IN} = V_{IH}$ (Max) |
| | D_0-D_5 | | | 240 | | |
| | CP_a, CP_b | | | 350 | | |
| I_{EE} | Power Supply Current | -129 | | -62 | mA | Inputs OPEN |

Note 3: The specified limits represent the "worst case" value for the parameter. Since these values normally occur at the temperature extremes, additional noise immunity and guardbanding can be achieved by decreasing the allowable system operating ranges. Conditions for testing shown in the tables are chosen to guarantee operation under "worst case" conditions.

DIP AC Electrical Characteristics

$V_{EE} = -4.2V$ to $-5.7V$, $V_{CC} = V_{CCA} = GND$

| Symbol | Parameter | $T_C = 0^\circ C$ | | $T_C = +25^\circ C$ | | $T_C = +85^\circ C$ | | Units | Conditions |
|-------------|------------------------|-------------------|------|---------------------|------|---------------------|------|-------|--------------|
| | | Min | Max | Min | Max | Min | Max | | |
| f_{MAX} | Toggle Frequency | 375 | | 375 | | 375 | | MHz | Figures 2, 3 |
| t_{PLH} | Propagation Delay | 0.80 | 2.00 | 0.80 | 2.0 | 0.90 | 2.10 | ns | Figures 1, 3 |
| t_{PHL} | CP_a, CP_b to Output | | | | | | | | |
| t_{PLH} | Propagation Delay | 1.10 | 2.30 | 1.10 | 2.30 | 1.20 | 2.40 | ns | Figures 1, 4 |
| t_{PHL} | MR to Output | | | | | | | | |
| t_{TLH} | Transition Time | 0.35 | 1.20 | 0.35 | 1.20 | 0.35 | 1.20 | ns | Figures 1, 3 |
| t_{THL} | 20% to 80%, 80% to 20% | | | | | | | | |
| t_S | Setup Time | | | | | | | | |
| | D_0-D_5 | 0.40 | | 0.40 | | 0.40 | | ns | Figure 5 |
| | MR (Release Time) | 1.60 | | 1.60 | | 1.60 | | | Figure 4 |
| t_H | Hold Time | | | | | | | | |
| | D_0-D_5 | 0.80 | | 0.80 | | 0.80 | | ns | Figure 5 |
| $t_{PW(H)}$ | Pulse Width HIGH | | | | | | | | |
| | CP_a, CP_b, MR | 2.00 | | 2.00 | | 2.00 | | ns | Figures 3, 4 |

Commercial Version (Continued) SOIC and PLCC AC Electrical Characteristics

$V_{EE} = -4.2V$ to $-5.7V$, $V_{CC} = V_{CCA} = GND$

| Symbol | Parameter | $T_C = 0^\circ C$ | | $T_C = +25^\circ C$ | | $T_C = +85^\circ C$ | | Units | Conditions |
|-------------|--|-------------------|------|---------------------|------|---------------------|------|-------|-----------------------|
| | | Min | Max | Min | Max | Min | Max | | |
| f_{MAX} | Toggle Frequency | 375 | | 375 | | 375 | | MHz | Figures 2, 3 |
| t_{PLH} | Propagation Delay | 0.80 | 1.80 | 0.80 | 1.80 | 0.90 | 1.90 | ns | Figures 1, 3 |
| t_{PHL} | CP_a , CP_b to Output | | | | | | | | |
| t_{PLH} | Propagation Delay | 1.10 | 2.10 | 1.10 | 2.10 | 1.20 | 2.20 | ns | Figures 1, 4 |
| t_{PHL} | MR to Output | | | | | | | | |
| t_{TLH} | Transition Time | 0.45 | 1.70 | 0.45 | 1.60 | 0.45 | 1.70 | ns | Figures 1, 3 |
| t_{THL} | 20% to 80%, 80% to 20% | | | | | | | | |
| t_S | Setup Time | | | | | | | | |
| | D_0 – D_5 | 0.30 | | 0.30 | | 0.30 | | ns | Figure 5 |
| | MR (Release Time) | 1.50 | | 1.50 | | 1.50 | | | Figure 4 |
| t_H | Hold Time | 0.80 | | 0.80 | | 0.80 | | ns | Figure 5 |
| | D_0 – D_5 | | | | | | | | |
| $t_{PW(H)}$ | Pulse Width HIGH | 2.00 | | 2.00 | | 2.00 | | ns | Figures 3, 4 |
| | CP_a , CP_b , MR | | | | | | | | |
| t_{OSHL} | Maximum Skew Common Edge Output-to-Output Variation Clock to Output Path | | 220 | | 220 | | 220 | ps | PLCC only (Note 4) |
| t_{OSLH} | Maximum Skew Common Edge Output-to-Output Variation Clock to Output Path | | 210 | | 210 | | 210 | ps | PLCC only (Note 4) |
| t_{OST} | Maximum Skew Opposite Edge Output-to-Output Variation Clock to Output Path | | 240 | | 240 | | 240 | ps | PLCC only (Note 4) |
| t_{PS} | Maximum Skew Pin (Signal) Transition Variation Clock to Output Path | | 230 | | 230 | | 230 | ps | PLCC only (Note 4) |

Note 4: Output-to-Output Skew is defined as the absolute value of the difference between the actual propagation delay for any outputs within the same packaged device. The specifications apply to any outputs switching in the same direction either HIGH-to-LOW (t_{OSHL}), or LOW-to-HIGH (t_{OSLH}), or in opposite directions both HL and LH (t_{OST}). Parameters t_{OST} and t_{PS} guaranteed by design.

Industrial Version**PLCC DC Electrical Characteristics**
 $V_{EE} = -4.2V$ to $-5.7V$, $V_{CC} = V_{CCA} = GND$, $T_C = 0^\circ C$ to $+85^\circ C$ (Note 5)

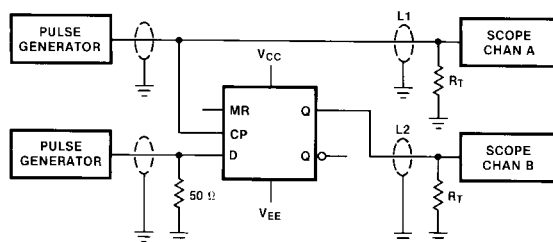
| Symbol | Parameter | $T_C = -40^\circ C$ | | $T_C = 0^\circ$ to $+85^\circ C$ | | Units | Conditions |
|-----------|---|---------------------|-------------------|----------------------------------|-------------------|-------|--|
| | | Min | Max | Min | Max | | |
| V_{OH} | Output HIGH Voltage | -1085 | -870 | -1025 | -870 | mV | $V_{IN} = V_{IH}$ (Max) or V_{IL} (Min) |
| V_{OL} | Output LOW Voltage | -1830 | -1575 | -1830 | -1620 | | Loading with 50Ω to -2.0V |
| V_{OHC} | Output HIGH Voltage | -1095 | | -1035 | | mV | $V_{IN} = V_{IH}$ (Min) or V_{IL} (Max) |
| V_{OLC} | Output LOW Voltage | | -1565 | | -1610 | | Loading with 50Ω to -2.0V |
| V_{IH} | Input HIGH Voltage | -1170 | -870 | -1165 | -870 | mV | Guaranteed HIGH Signal for All Inputs |
| V_{IL} | Input LOW Voltage | -1830 | -1480 | -1830 | -1475 | mV | Guaranteed LOW Signal for All Inputs |
| I_{IL} | Input LOW Current | 0.50 | | 0.50 | | μA | $V_{IN} = V_{IL}$ (Min) |
| I_{IH} | Input HIGH Current MR D ₀ -D ₅ CP _a , CP _b | | 350 240 350 | | 350 240 350 | μA | $V_{IN} = V_{IH}$ (Max) |
| I_{EE} | Power Supply Current | -129 | -62 | -129 | -62 | mA | Inputs OPEN |

Note 5: The specified limits represent the "worst case" value for the parameter. Since these values normally occur at the temperature extremes, additional noise immunity and guardbanding can be achieved by decreasing the allowable system operating ranges. Conditions for testing shown in the tables are chosen to guarantee operation under "worst case" conditions.

PLCC AC Electrical Characteristics
 $V_{EE} = -4.2V$ to $-5.7V$, $V_{CC} = V_{CCA} = GND$

| Symbol | Parameter | $T_C = -40^\circ C$ | | $T_C = +25^\circ C$ | | $T_C = +85^\circ C$ | | Units | Conditions |
|------------------------|--|---------------------|------|---------------------|------|---------------------|------|-------|--------------|
| | | Min | Max | Min | Max | Min | Max | | |
| f_{MAX} | Toggle Frequency | 375 | | 375 | | 375 | | MHz | Figures 2, 3 |
| t_{PLH} t_{PHL} | Propagation Delay CP _a , CP _b to Output | 0.80 | 1.80 | 0.80 | 1.80 | 0.90 | 1.90 | ns | Figures 1, 3 |
| t_{PLH} t_{PHL} | Propagation Delay MR to Output | 1.10 | 2.10 | 1.10 | 2.10 | 1.20 | 2.20 | ns | Figures 1, 4 |
| t_{TLH} t_{THL} | Transition Time 20% to 80%, 80% to 20% | 0.45 | 1.70 | 0.45 | 1.60 | 0.45 | 1.70 | ns | Figures 1, 3 |
| t_S | Setup Time D ₀ -D ₅ | 0.60 | | 0.30 | | 0.30 | | ns | Figure 5 |
| | MR (Release Time) | 2.20 | | 1.50 | | 1.50 | | | Figure 4 |
| t_H | Hold Time D ₀ -D ₅ | 0.60 | | 0.90 | | 0.90 | | ns | Figure 5 |
| $t_{PW(H)}$ | Pulse Width HIGH CP _a , CP _b , MR | 2.00 | | 2.00 | | 2.00 | | ns | Figures 3, 4 |

Test Circuitry



Notes:

$V_{CC}, V_{CCA} = +2V, V_{EE} = -2.5V$

L1 and L2 = equal length 50Ω impedance lines

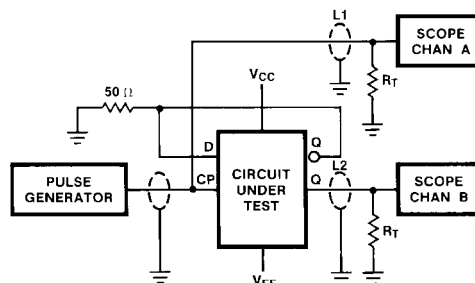
$R_T = 50\Omega$ terminator internal to scope

Decoupling 0.1 μF from GND to V_{CC} and V_{EE}

All unused outputs are loaded with 50Ω to GND

C_L = Fixture and stray capacitance ≤ 3 pF

FIGURE 1. AC Test Circuit



Notes:

$V_{CC}, V_{CCA} = +2V, V_{EE} = -2.5V$

L1 and L2 = equal length 50Ω impedance lines

$R_T = 50\Omega$ terminator internal to scope

Decoupling 0.1 μF from GND to V_{CC} and V_{EE}

All unused outputs are loaded with 50Ω to GND

C_L = Jig and stray capacitance ≤ 3 pF

FIGURE 2. Toggle Frequency Test Circuit

Switching Waveforms

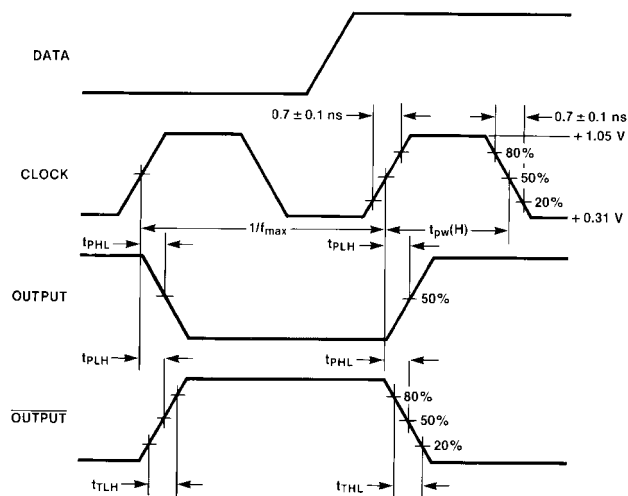


FIGURE 3. Propagation Delay (Clock) and Transition Times

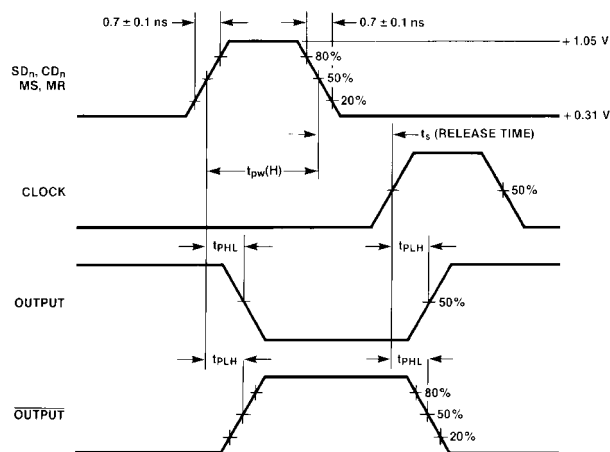
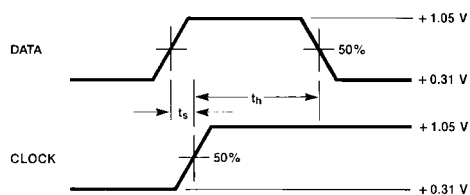


FIGURE 4. Propagation Delay (Reset)



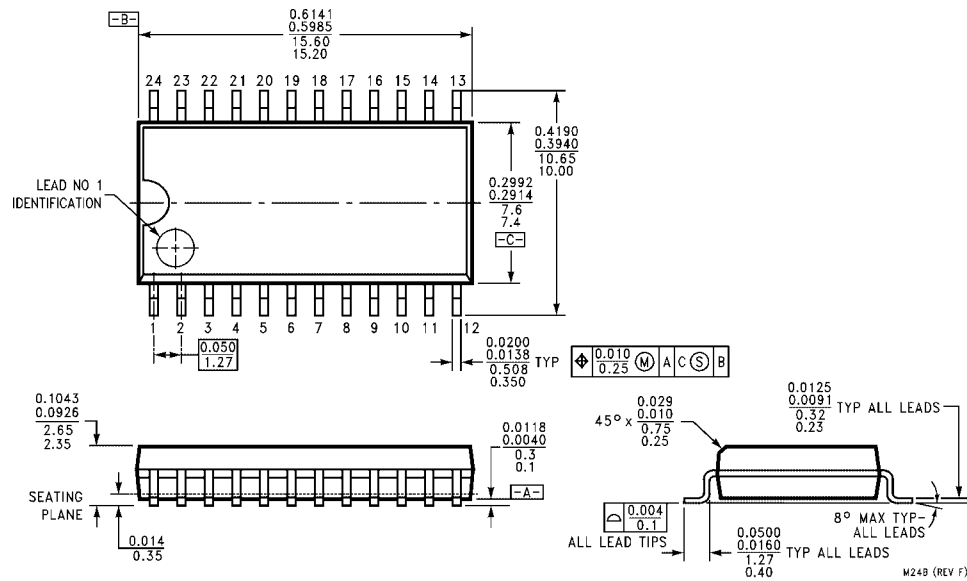
Notes:

t_s is the minimum time before the transition of the clock that information must be present at the data input.

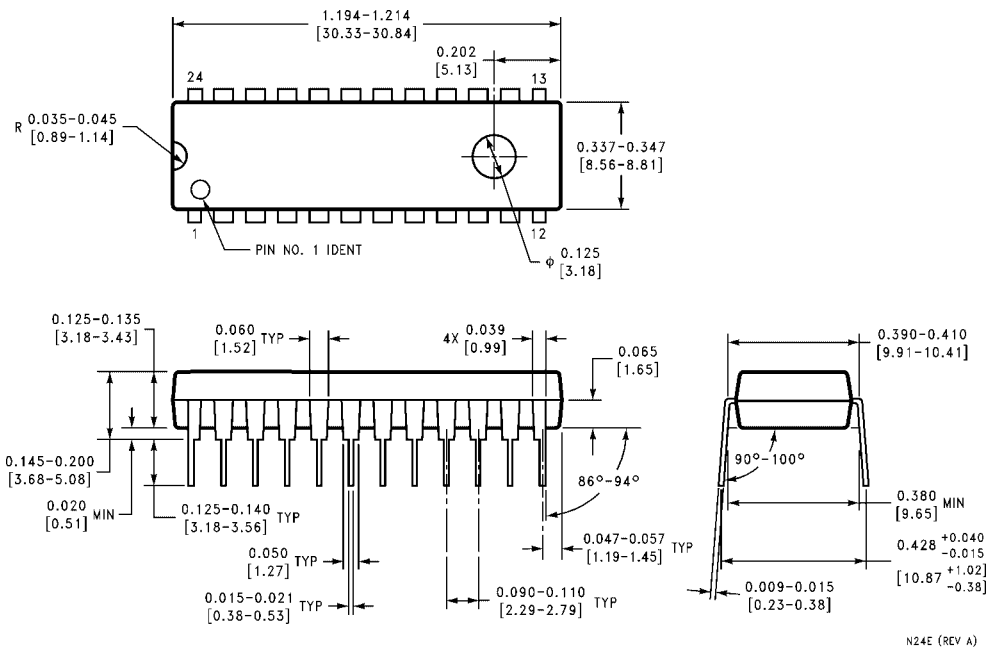
t_h is the minimum time after the transition of the clock that information must remain unchanged at the data input.

FIGURE 5. Setup and Hold Time

Physical Dimensions inches (millimeters) unless otherwise noted

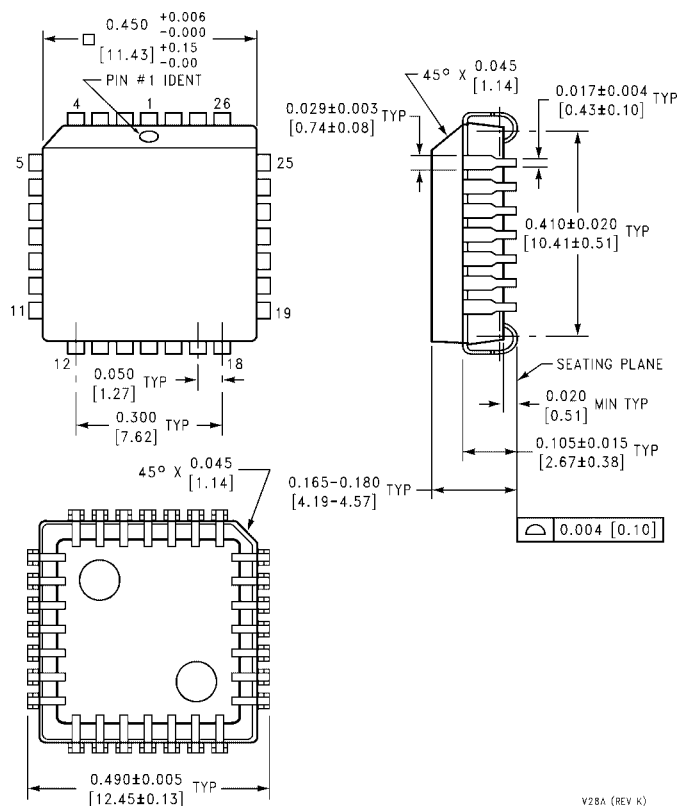


**24-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-013, 0.300 Wide
Package Number M24B**



**24-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-010, 0.400 Wide
Package Number N24E**

Physical Dimensions inches (millimeters) unless otherwise noted (Continued)



**28-Lead Plastic Lead Chip Carrier (PLCC), JEDEC MO-047, 0.450 Square
Package Number V28A**

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